

### WHO, HOW, WHAT?

**Participants:** Kids aged 6 to 10 years old (1st to 4th grade)

**Duration:** 30 minutes

**Number of participants:** Max. 12 kids (kids will work in pairs)

**Supervisor:** 1 workshop leader, 2 assistants

**Workshop material provided by Tinkerbots:** 6 Sensoric Mega Sets, 6 baseplans for Grabberbase model, 1 Tinkerbots sample, box with LEGO building bricks, name tags and certificates for participants

**Requirements for the location:** Room with tables and chairs, power outlets for charging the Powerbrains, list of participants with names and ages

**Level of difficulty:** Easy to medium

**Price of workshop:** Upon request

### EDUCATIONAL OBJECTIVES

#### Mechanical connections

- Functioning of each motion module: Turning (Twister), Bending (Pivot), Grabbing (Grabber)
- Action and reaction of different motion modules combined

#### Introduction to coding

- ‘Play & Record’ mode: Teaching the robots manually by recoding a sequence of movements

#### Playfully constructing robots

- Building the models following a manual and free building (optional)

#### Social interactions

- Collaboration and problem solving within the team



### ACTIVITIES OF THE WORKSHOP

#### Introduction

- Introduction of the leader and assistants, name tags for all participants
- Introduction to robots and programming
- Instruction on how to put together the different modules
- Presentation of motion modules and Powerbrain, functioning of each module

**Building the Grabberbase** • Building the “Small Grabberbase” model following the manual and workshop leader’s instruction

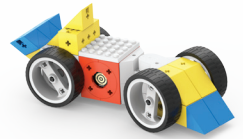
**Teaching #1** • Teaching the Grabber how pick up an object and put it back down

**Teaching #2** • Teaching the Grabber how to pick up a brick and throw it away

**Free building** • Customizing the Grabberbase model with LEGO and Cubie bricks

**Presentation** • Each teams presents its robots and shows the movements it has taught the robot, every participant receives a certificate as robot constructor

**End** • Summary, Giving-out of certificates and goodbyes



### WHO, HOW, WHAT?

**Participants:** Kids aged 6 to 10 years old (1st to 4th grade)

**Duration:** 30 minutes

**Number of participants:** Max. 12 kids (kids will work in pairs)

**Supervisor:** 1 workshop leader, 2 assistants

**Workshop material provided by Tinkerbots:** 6 Advanced Builder Sets, 1 Tinkerbots sample, box with LEGO building bricks, 6 smartphones or tablets, tape for creating a racing track, name tags and certificates for participants

**Requirements for the location:** Room with tables and chairs, power outlets for charging the Powerbrains, space to race the cars on the floor, list of participants with names and ages

**Level of difficulty:** Easy to medium

**Price of workshop:** Upon request

### EDUCATIONAL OBJECTIVES

#### Mechanical connections

- Functioning of each motion module: Accelerating (Motor), Bending and steering (Pivot)
- Action and reaction of different motion modules combined

#### Introduction to coding

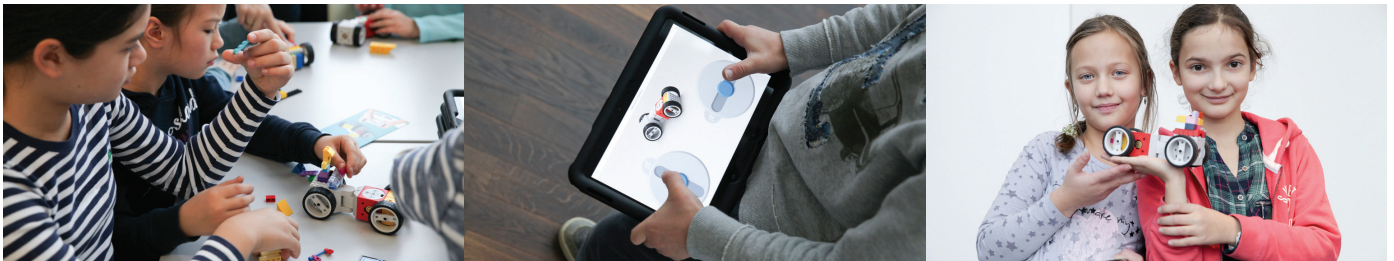
- ‘Play & Record’ mode: Teaching the robots manually by recoding a sequence of movements

#### Playfully constructing robots

- Building the models following a manual and free building (optional)

#### Social interactions

- Collaboration and problem solving within the team



### ACTIVITIES OF THE WORKSHOP

#### Introduction

- Introduction of the leader and assistants, name tags for all participants
- Introduction to robots and programming
- Instruction on how to put together the different modules
- Presentation of motion modules and Powerbrain, functioning of each module

**Building the Racer** • Building the “Racer” model following the manual and workshop leader’s instruction

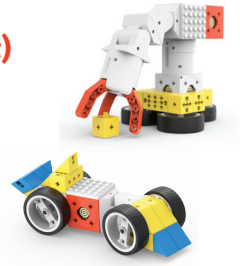
**Teaching #1** • Teaching the Racer how to drive in the form of an 8 (two loops)

**Steering via app** • Remotely controlling the Racer through our App, using the Gyro-steering, driving in the form of an 8

**Free building** • Customizing the Racer model with LEGO and Cubie bricks

**Presentation and Race** • Each team presents its robots and races through the track (stopping the time), every participant receives a certificate as robot constructor

**End** • Summary, Giving-out of certificates and goodbyes

**WHO, HOW, WHAT?**

**Participants:** Kids aged 6 to 10 years old (1st to 4th grade)

**Duration:** 60 minutes

**Number of participants:** Max. 12 kids (kids will work in pairs)

**Supervisor:** 1 workshop leader, 2 assistants

**Workshop material provided by Tinkerbots:** 6 Sensoric Mega Sets, 6 baseplans for Grabberbase model, 1 Tinkerbots sample, box with LEGO building bricks, name tags and certificates for participants

**Requirements for the location:** Room with tables and chairs, power outlets for charging the Powerbrains, list of participants with names and ages

**Level of difficulty:** medium

**Price of workshop:** Upon request

**EDUCATIONAL OBJECTIVES****Mechanical connections**

- Functioning of each motion module: Turning (Twister), Bending (Pivot), Grabbing (Grabber), Accelerating (Motor)
- Action and reaction of different motion modules combined

**Introduction to coding**

- ‘Play & Record’ mode: Teaching the robots manually by recoding a sequence of movements

**Playfully constructing robots**

- Building the models following a manual and free building (optional)

**Social interactions**

- Collaboration and problem solving within the team

**ACTIVITIES OF THE WORKSHOP****Introduction**

- Introduction of the leader and assistants, name tags for all participants
- Introduction to robots and programming
- Instruction on how to put together the different modules
- Presentation of motion modules and Powerbrain, functioning of each module

**Building the Grabberbase** • Building the “Small Grabberbase’ model following the manual and workshop leader’s instruction

**Teaching #1** • Teaching the Grabber how pick up an object and put it back down

**Building the Racer** • Take apart the Grabberbase and build the Racer model following the manual

**Teaching #2** • Teaching the Racer how to drive in the form of an 8 (two loops)

**Free building and combining the Grabber and Racer** • Customizing the models with LEGO and Cubie bricks, free combination of the two models (How can the Racer and Grabber be connected?)

**Presentation** • Each team presents its robot and explains its functions, every participant receives a certificate as robot constructor

**End** • Summary, Giving-out of certificates and goodbyes





## WHO, HOW, WHAT?

**Participants:** Kids aged 8 to 10 years old (3rd to 4th grade)

**Duration:** 60 minutes

**Number of participants:** Max. 12 kids (kids will work in pairs)

**Supervisor:** 1 workshop leader, 2 assistants

**Workshop material provided by Tinkerbots:** 6 Sensoric Mega Sets, 1 Tinkerbots sample, box with LEGO building bricks, name tags and certificates for participants, cards with missions

**Requirements for the location:** Room with tables and chairs, power outlets for charging the Powerbrains, list of participants with names and ages

**Level of difficulty:** Medium to hard

**Price of workshop:** Upon request

## EDUCATIONAL OBJECTIVES

### Mechanical connections

- Functioning of each motion module: Turning (Twister), Bending (Pivot), Grabbing (Grabber), Accelerating (Motor), Controlling (IR Sensor)
- Action and reaction of different motion modules combined

### Coding

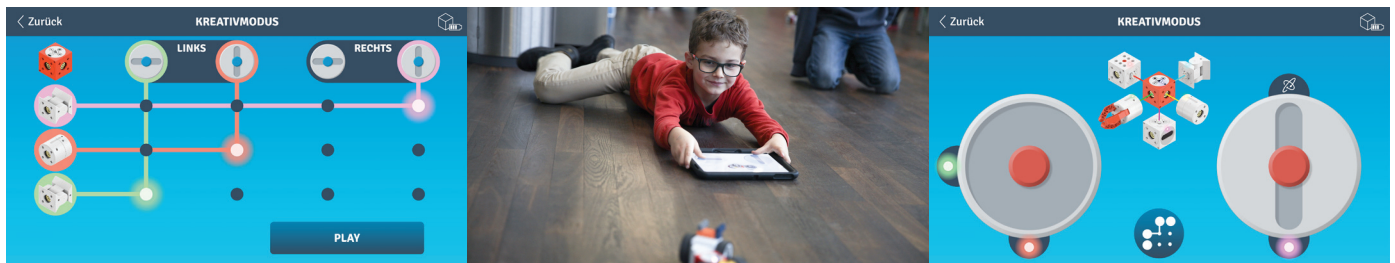
- Combining the modules per App, Understanding of programming, Controlling via sensors

### Playfully constructing robots

- Building the models following a manual and free building (optional)

### Social interactions

- Collaboration and problem solving within the team



## ACTIVITIES OF THE WORKSHOP

### Introduction

- Introduction of the leader and assistants, name tags for all participants
- Introduction to robots and programming
- Instruction on how to put together the different modules
- Presentation of motion modules and Powerbrain, functioning of each module
- Presentation of the model (Teaching) and explication of the app

### Free building of a model, introduction of the 'mission

- With the help of the workshop leader and assistants: What do I want my robot to be able to do, how shall it move, how do I want to control it? In what kind of environment can the robot be? (missioncards: Moon landscape, Farm, Construction site)

### Controlling via Appn

- Combining different motion modules in the creative mode, steering and switching modules, steering through the IR sensor (optional re-building the model, customizing it with LEGO bricks)

**Presentation** • Each teams presents its robot and explains its functions, every participant receives a certificate as robot constructor

**End** • Summary, Giving-out of certificates and goodbyes